

Year 13 Further Maths – Further Pure 1 Option

Topic		Ref	Ex
Inequalities	Solving Inequalities <ul style="list-style-type: none"> Solve inequalities involving modulus signs 	FP7.1	4C
Conic Sections 2	Ellipses <ul style="list-style-type: none"> Know and use the Cartesian equation for the ellipse Know and use the parametric equations for the ellipse, including a general point on the curve Understand the focus-directrix property of the ellipse – i.e. it is the locus of points equidistant from the focus and directrix. 	FP4.1 FP4.2 FP4.3	3A 3C
	Hyperbolas <ul style="list-style-type: none"> Know and use the Cartesian equation for a standard hyperbola Know and use the parametric equations for a standard hyperbola, including a general point on the curve Understand the focus-directrix property of the hyperbola – i.e. it is the locus of points equidistant from the focus and directrix. 	FP4.1 FP4.2 FP4.3	3B
	Eccentricity <ul style="list-style-type: none"> Understand the eccentricity as the ratio of the distance from a fixed point (focus) and a fixed line (directrix) for a conic section. Be able to calculate the eccentricity Know the value to expect for the eccentricity of an ellipse, parabola or hyperbola. 	FP4.2	3C
	Tangents and Normals <ul style="list-style-type: none"> Find the equations of tangents and normals to ellipses and hyperbolas. Note: for AS level, the gradient function dy/dx will be provided for a parabola. 	FP4.3	3D 3E
	Loci <ul style="list-style-type: none"> Use the focus-directrix property of an ellipse or hyperbola to derive its general equation from a given point (focus) and straight line (directrix) 	FP4.4	3F
Numerical Methods	Simpson's rule <ul style="list-style-type: none"> Use Simpson's rule to find an approximation for a given definite integral 	FP6.2	8D
Reducible Differential Equations	First Order DEs <ul style="list-style-type: none"> Use a given substitution to transform a first order DE equation into one that can be solved 	FP3.2	9A
	Second Order DEs <ul style="list-style-type: none"> Use a given substitution to transform a second order DE equation into one that can be solved 	FP3.2	9B
	Modelling with DEs <ul style="list-style-type: none"> Solve modelling problems involving reducible DEs 	FP3.2	9C

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Taylor series	Derive Taylor series <ul style="list-style-type: none"> • Derive Taylor series for functions • Understand that the Taylor series $f(x + a)$ allows you to approximate the value of $f(x)$ close to $x = a$. 	FP2.1	6A
	Use Taylor series <ul style="list-style-type: none"> • Use series expansions to evaluate limits • Use the Taylor series method to find a series solution to a Differential Equation 	FP2.2 FP3.1	6B 6C
Further calculus	Leibnitz's theorem <ul style="list-style-type: none"> • Apply Leibnitz's theorem for differentiating products • Use it to find an expression for the nth derivative of a product of functions 	FP2.3	7A
	L'Hospital's rule <ul style="list-style-type: none"> • Understand the use of derivatives to evaluate limits of indeterminate forms. 	FP2.4	7B
	Weierstrass substitution <ul style="list-style-type: none"> • Use tangent half-angle substitutions to find definite and indefinite integrals using Weierstrass substitution $t = \tan \frac{x}{2}$	FP2.5	7C
Vectors	Straight lines <ul style="list-style-type: none"> • Write the vector equation of a straight line in the form $(\mathbf{r} - \mathbf{a}) \times \mathbf{b} = \mathbf{0}$ • Find the direction ratios and direction cosines of a line 	FP5.3	1D
	3D geometry problems <ul style="list-style-type: none"> • Use vectors involving points, lines and planes to solve 3D geometry problems 	FP5.3	1E